# University of Alabama <br> Department of Physics and Astronomy 

## Problem Set 4 due 21 Sept 2018

## Instructions:

1. Answer all questions below (bonus questions optional).
2. Show your work for full credit.
3. All problems are due by $11: 59 \mathrm{pm}$ on 21 Sept 2018.
4. You may collaborate, but everyone must turn in their own work.
5. The potential energy of two atoms in a molecule can sometimes be approximated by the Morse potential,

$$
\begin{equation*}
U(r)=A\left[\left(e^{-(r-R) / S}-1\right)^{2}-1\right] \tag{1}
\end{equation*}
$$

where $r$ is the distance between the two atoms and $A, R$, and $S$ are positive constants with $S \ll R$. (a) Sketch this function for $0<r<\infty$. (b) Find the equilibrium separation $r_{o}$, at which $U(r)$ is minimum. (c) Now write $r=r_{o}+x$ so that $x$ is the displacement from equilibrium, and show that for small displacements, $U$ has the approximate form $U=$ const $+\frac{1}{2} k x^{2}$. That is, Hooke's law applies. (d) What is the force constant $k$ ? (bonus $+\mathbf{5}$ ) Interpret $R, S$, and $A$ physically in terms of characteristic properties of diatomic molecules. Hint: the Morse potential is well known.
2. An unusual pendulum is made by fixing a string to a horizontal cylinder of radius $R$, wrapping the string several times around the cylinder, and then tying a mass $m$ to the loose end. In equilibrium, the mass hangs a distance $l_{o}$ vertically below the edge of the cylinder. (a) Find the potential energy if the pendulum has swung to an angle $\varphi$ from the vertical. (b) Show that for small angles, it can be written in Hooke's law form $U=\frac{1}{2} k \varphi^{2}$. (c) Comment on the value of $k$. Hint: Draw $a$ figure, understand the geometry. At an angle $\varphi$, what length of rope is wrapped around the cylinder compared to when $\varphi=0$ ? The remaining length helps you find the height.
3. A practical sort of problem. You are told that at known positions $x_{1}$ and $x_{2}$, an oscillating mass $m$ has speeds $v_{1}$ and $v_{2}$. What are the amplitude and angular frequency of the oscillations?
4. The potential energy of a one-dimensional mass $m$ at a distance $r$ from the origin is

$$
\begin{equation*}
U(r)=U_{o}\left(\frac{r}{R}+\lambda^{2} \frac{R}{r}\right) \tag{2}
\end{equation*}
$$

for $0<r<\infty$, with $U_{o}, R$, and $\lambda$ all positive constants. (a) Find the equilibrium position $r_{o}$. (b) Let $x$ be the distance from equilibrium and show that, for small $x$, the PE has the form
$U=$ const $+\frac{1}{2} k x^{2}$. (c) What is the angular frequency of small oscillations? Hint: for small displacements, Taylor expand $U$ about $r_{o}$ and focus on the second-order term. The constant term can be defined to zero by a suitable choice of zero potential energy. What must be true of the first-order term in equilibrium?
5. Consider a two-dimensional anisotropic oscillator with motion given by

$$
\begin{align*}
x(t) & =A_{x} \cos \left(\omega_{x} t\right)  \tag{3}\\
y(t) & =A_{y} \cos \left(\omega_{y} t-\delta\right) \tag{4}
\end{align*}
$$

(a) Prove that if the ratio of frequencies is rational (that is, $\omega_{x} / \omega_{y}=p / q$ where $p$ and $q$ are integers) then the motion is periodic. What is the period? (b) Prove that if the same ratio is irrational, the motion never repeats itself.
6. A damped oscillator satisfies the equation

$$
\begin{equation*}
m \ddot{x}+b \dot{x}+k x=0 \tag{5}
\end{equation*}
$$

where $F_{\text {damp }}=-b \dot{x}$ is the damping force. Find the rate of change of the energy $E=\frac{1}{2} m \dot{x}^{2}+\frac{1}{2} k x^{2}$ (by straightforward differentiation), and, with the help of the equation above, show that $d E / d T$ is (minus) the rate at which energy is dissipated by $F_{\text {damp }}$.
7. An undamped oscillator has period $\tau_{o}=1.000 \mathrm{~s}$, but I now add a little damping so that its period changes to $\tau_{1}=1.001 \mathrm{~s}$. (a) What is the damping factor $\beta$ ? (b) By what factor will the amplitude of oscillation decrease after 10 cycles? (c) Which effect of damping would be more noticeable, the change in period or the decrease in amplitude? Justify your answer.
8. The solution for $x(t)$ for a driven, underdamped oscillator is most conveniently found in the form

$$
\begin{equation*}
x(t)=A \cos (\omega t-\delta)+e^{-\beta t}\left[B_{1} \cos \left(\omega_{1} t\right)+B_{2} \sin \left(\omega_{1} t\right)\right] \tag{6}
\end{equation*}
$$

Solve the equation above and the corresponding expression for $\dot{x}$, to give the coefficients $B_{1}$ and $B_{2}$ in terms of $A, \delta$, and the initial position and velocity $x_{o}$ and $v_{o}$. You should reproduce the expressions given in Example 5.3 in your textbook.
9. We know that if the driving frequency $\omega$ is varied, the maximum response $\left(A^{2}\right)$ of a driven damped oscillator occurs at $\omega \approx \omega_{o}$ (if the natural frequency is $\omega_{o}$, and the damping constant $\left.\beta \ll \omega_{o}\right)$. Show that $A^{2}$ is equal to half its maximum value when $\omega \approx \omega_{o} \pm \beta$, so that the full width at half maximum is just $2 \beta$. [Hint: be careful with your approximations. For instance, it is fine to say $\omega+\omega_{o} \approx 2 \omega_{o}$, but you certainly can't say $\omega-\omega_{o} \approx 0$.]
10. Another interpretation of the $Q$ of a resonance comes from the following: Consider the motion of a driven damped oscillator after any transients have died out, and suppose that it is being driven close to resonance so you can set $\omega=\omega_{o}$. (a) Show that the oscillator's total energy (kinetic plus potential) is $E=\frac{1}{2} m \omega^{2} A^{2}$. (b) Show that the energy $\Delta E_{\text {dis }}$ dissipated during one cycle by the damping force $F_{\text {damp }}$ is $2 \pi m \beta \omega A^{2}$. (Remember that the rate at which a force does work is $F v$.) (c) Hence show that $Q$ is $2 \pi$ times the ratio of $E / \Delta E_{\text {dis }}$.
11. BONUS +10 : Consider a cart on a spring with natural frequency $\omega_{o}=2 \pi$, which is released from rest at $x_{o}=1$ and $t=0$. Using appropriate software, plot the position $x(t)$ for $0<t<2$ and for damping constants $\beta=0,1,2,4,6,2 \pi, 10,20$. [Remember that $x(t)$ is given by different formulas for $\beta<\omega_{o}, \beta=\omega_{o}$, and $\beta>\omega_{o}$.]

