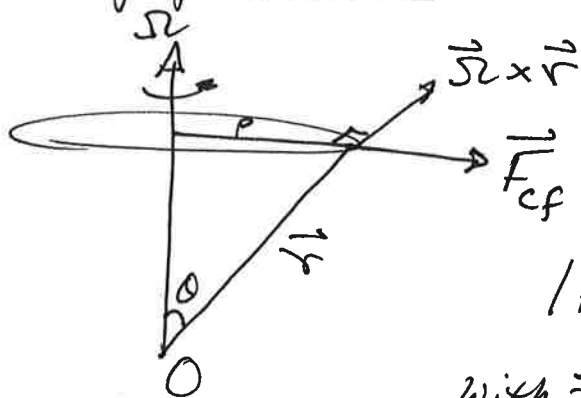


# Centrifugal force



$\vec{F}_{cf} = m(\vec{\Omega} \times \vec{r}) \times \vec{\Omega}$  radially outward  
 $|\vec{F}_{cf}| = m\Omega^2 \rho$  in  $\hat{\rho}$  dir

with  $\vec{v}_t = \vec{\Omega} \times \vec{r}$ ,  $v_t = \Omega \rho$  and  $F_{cf} = \frac{mv_t^2}{\rho}$

Free fall acceleration:  $\vec{g}$  is surprisingly complicated now relative to earth,

$m\ddot{\vec{r}} = \vec{F}_{grav} + \vec{F}_{cf} = -\frac{GMm}{R^2} \hat{r} + m\Omega^2 \rho \hat{\rho}$

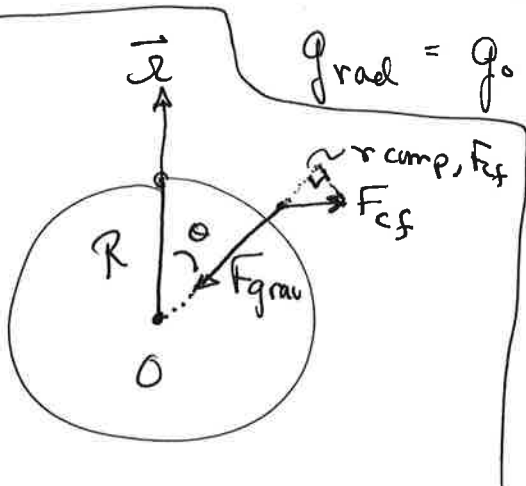
Let  $m\vec{g}_0 = -\frac{GMm}{R^2} \hat{r}$  - "true" grav force, what we'd see w/o rotation  
 hmm... not in same direction!

effective force is then  $m\ddot{\vec{r}} = \vec{F}_{eff} = m\vec{g}_0 + m\Omega^2 R \sin\theta \hat{\rho}$  ( $\rho = R \sin\theta$ )

and accel: (effective)  $\vec{g} = \vec{g}_0 + \Omega^2 R \sin\theta \hat{\rho}$

- the purely radial part projects  $\hat{\rho}$  component along  $\hat{r}$  (multiply by  $\sin\theta$ )

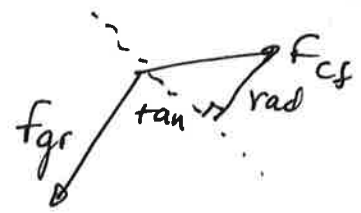
$g_{rad} = g_0 - \Omega^2 R \sin^2\theta$



zero at poles ( $\theta = 0, \pi$ )

max at equator.  $\Omega^2 R \sim 0.034 \text{ m/s}^2$   
 (0.3% less @ equ.)

there must also be a tangential part though - the cos  $\theta$  comp



$$g_{tan} = \Omega^2 R \sin \theta \cos \theta \leftarrow \text{zero @ poles; equator max at } 45^\circ$$

$\Rightarrow$  free fall accel is NOT in the direction of grav. force!  
there is a sideways component to free-fall accel!

$$\text{angle btw } \vec{g}, \vec{g}_0 = \alpha \approx \frac{g_{tan}}{g_{rad}} \Big|_{\theta=45} = \frac{\Omega^2 R}{2g} \approx 0.1^\circ$$

- actually quite hard to measure - any reasonable definition of "vertical" to define  $\vec{g}_0$  winds up being subject to same tangential force
- define vertical = along  $\vec{g}$  for practical reasons  
 $hoy = \perp \vec{g}$
- usually an irrelevant distinction btw  $\vec{g}, \vec{g}_0$

Coriolis Force - we needed a second inertial force in a rot. frame

$$\vec{F}_{cor} = 2m\vec{v} \times \vec{\Omega} = 2m\vec{v} \times \vec{\Omega} \quad \text{looks very much like } \vec{F} = q\vec{v} \times \vec{B}!$$

- no deep significance, but will help w/ visualization
- can suspect this will curve projectile trajectories

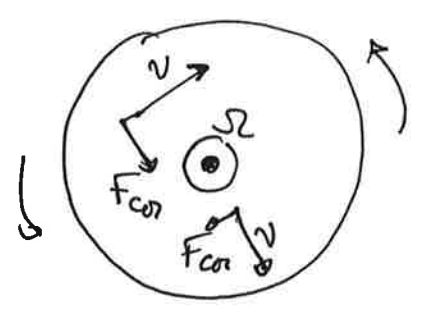
how big?  $\Omega \sim 7 \times 10^{-5} \text{ s}^{-1}$  from before

say baseball @ 50 m/s,  $a_{max} = \frac{F_{cor}}{m} \sim 2v\Omega \sim 7 \times 10^{-3} \text{ m/s}^2$

negl. compared to  $g$  or air resistance

Coriolis will be relevant for very fast, long-range projectiles  
- or - when it acts over a long time, e.g. Foucault pendulum

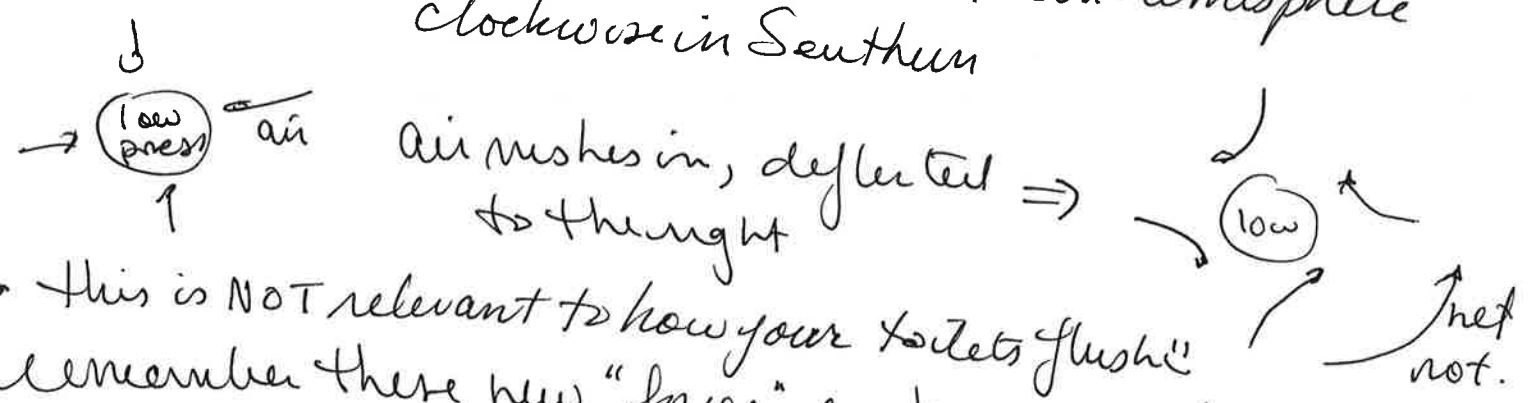
Direction: like magnetic force,  $2m\vec{v} \times \vec{\Omega}$  is always  $\perp \vec{v}$   
and also  $\perp$  to  $\vec{\Omega}$



- for counterclockwise rotation,  $\Omega$  is out of the board, so  $\vec{F}_{Cor}$  will lie in plane
- for ccw, deflection is always to the right (left for clockwise rot) - like magn force

• this could be northern hemisphere viewed from above  
Coriolis deflects bodies to right  
(to left in Southern hemisphere)

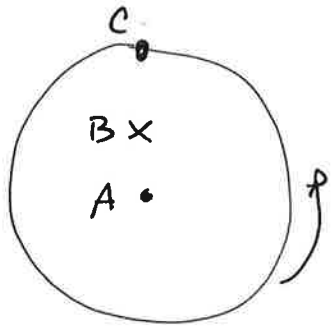
- long-range weaponry - have to adjust aim for this
- cyclones! Counterclockwise in northern hemisphere  
clockwise in Southern



- this is NOT relevant to how your toilets flush!
- remember these new "forces" are kinematic forces resulting from our using an accelerated frame as POV
- may be easier to analyze in non-inertial frame and "translate" to rot frame (recall: pendulum in elevator)

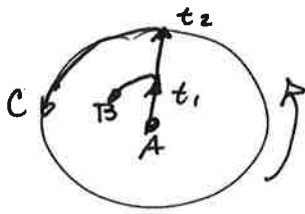
# Motion on a turntable

3 observers A, B, C are in line on a turntable

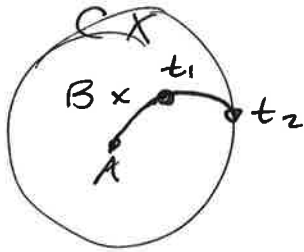


- kick a frictionless puck from center
- A kicks it exactly toward B, but by the time it gets there B has moved C moves even more

- net force in any inertial frame is zero
- in the inertial frame, puck travels in a straight line as B, C, rotate away w/ turntable



- in non inertial frame we have
  - centrifugal - radially outward, incl. to path
  - Coriolis - deflects to right!



- ⇒ in rotating frame A, B, C remain in line puck is deflected to right
- much clearer to analyze in ground-based frame

• this 2D example is nice & simple; rarely s = w /  $F_{cf}$  and  $F_{cor}$  usually complicated and messy

# Free-Fall? Coriolis close to earth's surface

Since centrifugal > Coriolis, have to include both

$$m \ddot{\vec{r}} = m \vec{g}_0 + \vec{F}_{cf} + \vec{F}_{cor} \quad \text{---} \quad 2m \vec{v} \times \vec{\Omega}$$

true force of earth's grav.  $m(\vec{\Omega} \times \vec{r}) \times \vec{\Omega}$

can approx  $\vec{r}$  by  $\vec{R}$

$\vec{r}$  = posn rel center of earth  
 $\vec{R}$  = point on surface

$$\Rightarrow F_{cf} = m(\vec{\Omega} \times \vec{R}) \times \vec{\Omega}$$

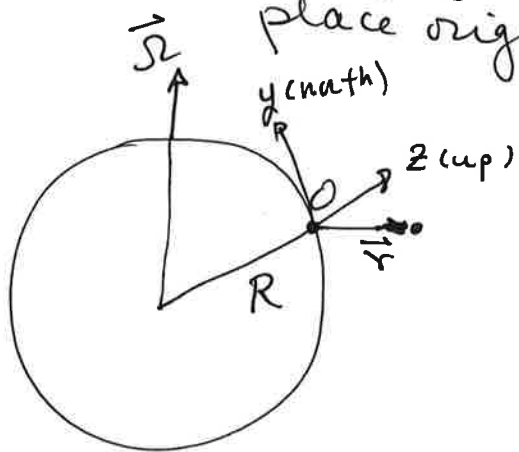
• now recall  $m \vec{g}_0 + \vec{F}_{cf} = m \vec{g}$  where  $\vec{g}$  is observed free fall accel we can actually see

• that means we can eliminate  $F_{cf}$  if we realize we're already incorporated it into our measurement of  $\vec{g}$ !

$$\Rightarrow \ddot{\vec{r}} = \vec{g} + 2\vec{v} \times \vec{\Omega} = \vec{g} + 2\dot{\vec{r}} \times \vec{\Omega}$$

doesn't involve  $r$  at all, only  $\dot{r}$  and  $\ddot{r}$ !

$\Rightarrow$  change of origin is irrelevant, so we may as well place origin on earth's surface at  $\vec{R}$



$y = \text{north}, z = \text{up}, x = \text{east}$

now  $\dot{\vec{r}} = (\dot{x}, \dot{y}, \dot{z})$

$$\vec{R} = (0, R \sin \theta, R \cos \theta)$$

$$\Rightarrow \dot{\vec{r}} \times \vec{\Omega} = (\dot{y} R \cos \theta - \dot{z} R \sin \theta, -\dot{x} R \sin \theta, \dot{x} R \sin \theta)$$

$$\Rightarrow \begin{aligned} \ddot{x} &= 2R(\dot{y} \cos \theta - \dot{z} \sin \theta) \\ \ddot{y} &= -2R\dot{x} \cos \theta \end{aligned}$$

$$\ddot{z} = -g + 2R\dot{x} \sin \theta$$

need some approximations

- $\Omega$  is small. if we ignore it entirely?

$$\ddot{x} = \ddot{y} = 0 \quad \ddot{z} = -g \Rightarrow \text{intro projectile motion}$$

This is 0<sup>th</sup> order approx, just ignore ( $\Omega$  accuracy)  
 $\Rightarrow x = 0 = y, z = h - \frac{1}{2}gt^2$  dropped from h

- next order approx:

- use 0<sup>th</sup> order approx for  $\dot{x}, \dot{y}, \dot{z}$

$$\Rightarrow \dot{x} \approx \dot{y} \approx 0 \quad \dot{z} = -gt$$

using this

$$\ddot{x} \approx 2\Omega g t \sin\theta \quad \leftarrow \text{my new one!}$$

$$\ddot{y} \approx 0$$

$$\ddot{z} \approx -g$$

- integrate twice,  $x = \frac{1}{3}\Omega g t^3 \sin\theta$  ( $y = 0, z = h - \frac{1}{2}gt^2$ )  
- first order approx, good to  $\Omega^1$  as in 0<sup>th</sup> order approx.  
- extra displacement to east we didn't expect before

Let's say we drop something from 100m.

- from z, time to bottom is as always,  $t = \sqrt{2h/g}$
- total easterly deflection ( $\theta = 90^\circ$ , equator;  $g \approx 10 \text{ m/s}^2$ )

$$x \approx \frac{1}{3} (7 \times 10^{-5} \text{ s}^{-1}) (10 \frac{\text{m}}{\text{s}^2}) (20 \text{ s}^2)^{3/2} \approx 2.2 \text{ cm}$$

- Small, but totally observable
- Predicted by Newton, verified by his rival Hooke (later 1685)  
not properly explained until Coriolis (1835)