

Name _____

PH105-004 Final Exam

Instructions

1. Answer all questions.
2. Record your responses on a scantron sheet.
3. On your scantron sheet, be sure to bubble in your **full name and CWID**.

1. A car accelerates from 10.0 m/s to 30.0 m/s at a rate of 3.00 m/s². How far does the car travel while accelerating?

- (a) *133 m (b) 80.0 m (c) 226 m (d) 399 m (e) 6.67 m

2. A ball is thrown at a 60.0° angle above the horizontal across level ground. It is thrown from a height of 2.00 m above the ground with a speed of 20.0 m/s and experiences no appreciable air resistance. Take $g=9.8\text{ m/s}^2$. The time the ball remains in the air before striking the ground is closest to

- (a) *3.64 s. (b) 3.07 s. (c) 3.32 s. (d) 3.53 s. (e) 16.2 s.

3. A 60.0-kg person rides in an elevator while standing on a scale. The scale reads 400 N. The acceleration of the elevator is closest to

- (a) zero. (b) 9.80 m/s² downward. (c) 6.67 m/s² upward. (d) 6.67 m/s² downward.
(e) *3.13 m/s² downward.

4. A spring stretches by 21.0 cm when a 135 N object is attached. What is the weight of a fish that would stretch the spring by 31.0 cm? (a) 91.0 N (b) 279 N (c) 145 N (d) *199 N (e) 305 N

5. A massless rope passes over a frictionless, massless pulley suspended from the ceiling. A 4 kg block is attached to one end and a 5 kg block is attached to the other end. The magnitude of the acceleration of the 5 kg block is:

- (a) g/4 (b) 5g/9 (c) 4g/9 (d) g/5 (e) *g/9

6. Two ice skaters push off against one another starting from a stationary position. The 45.0-kg skater acquires a speed of 0.375 m/s. What speed does the 60.0-kg skater acquire? Assume that any other unbalanced forces during the collision are negligible.

- (a) 0.375 m/s (b) 0.500 m/s (c) 0.750 m/s (d) *0.281 m/s (e) 0.000 m/s

7. A 620-g object traveling at 2.1 m/s collides head-on with a 320-g object traveling in the opposite direction at 3.8 m/s. If the collision is perfectly elastic, what is the change in the kinetic energy of the 620-g object?

- (a) It gains 0.69 J. (b) It loses 1.4 J. (c) It loses 0.47 J. (d) *It loses 0.23 J.
(e) It doesn't lose any kinetic energy because the collision is elastic.

8. A tennis ball bounces on the floor three times. If each time it loses 22.0% of its energy due to heating, how high does it rise after the third bounce, provided we released it 2.3 m from the floor?

Name

- (a) 11 cm (b) 110 mm (c) 140 cm (d) *110 cm (e) 24 mm

9. A 2.00-kg object traveling east at 20.0 m/s collides with a 3.00-kg object traveling west at 10.0 m/s. After the collision, the 2.00-kg object has a velocity 5.00 m/s to the west. How much kinetic energy was lost during the collision?

- (a) 91.7 J (b) *458 J (c) 0.000 J (d) 516 J (e) 175 J

10. A potter's wheel, with rotational inertia $46 \text{ kg}\cdot\text{m}^2$, is spinning freely at 40 rpm. The potter drops a lump of clay onto the wheel, where it sticks a distance 1.2 m from the rotational axis. If the subsequent angular speed of the wheel and clay is 32 rpm what is the mass of the clay? The rotational inertia of a disc is $\frac{1}{2}mR^2$, where R is the radius of the disc, while the rotational inertia of a point particle is mR^2 , where R is the distance of the particle to the center of rotation.

- (a) 5.4 kg (b) *8.0 kg (c) 8.8 kg (d) 7.0 kg (e) 9.2 kg

11. A uniform solid cylinder of radius R and a thin uniform spherical shell of radius R both roll without slipping. If both objects have the same mass and the same kinetic energy, what is the ratio of the linear speed of the cylinder to the linear speed of the spherical shell? A cylinder of radius R and mass M has a rotational inertia of $\frac{1}{2}MR^2$, a spherical shell of the same radius and mass has a rotational inertia $\frac{2}{3}MR^2$.

- (a) $\frac{4}{\sqrt{3}}$ (b) $*\frac{\sqrt{10}}{2}$ (c) $\frac{\sqrt{3}}{2}$ (d) $\sqrt{\frac{4}{3}}$ (e) $\frac{4}{3}$

12. A 0.25 kg ideal harmonic oscillator has a total mechanical energy of 4.0 J. If the oscillation amplitude is 20.0 cm, what is the oscillation frequency?

- (a) *4.5 Hz (b) 3.2 Hz (c) 1.4 Hz (d) 2.3 Hz (e) 5.7 Hz

13. Waves travel along a 100-m length of string which has a mass of 55 g and is held taut with a tension of 75 N. What is the speed of the waves?

- (a) 3.7 m/s (b) 37 m/s (c) 0.37 m/s (d) *370 m/s (e) 3700 m/s

14. A bag of potato chips contains 2.00 L of air when it is sealed at sea level at a pressure of 1.00 atm and a temperature of 20.0°C . What will be the volume of the air in the bag if you take it with you, still sealed, to the mountains where the temperature is 7.00°C and atmospheric pressure is 70.0 kPa? Assume that the bag behaves like a balloon and that the air in the bag is in thermal equilibrium with the outside air. (1 atm = $1.01 \times 10^5 \text{ Pa}$)

- (a) 1.01 L (b) 1.38 L (c) *2.76 L (d) 4.13 L (e) 3.84 L

15. An ideal gas has initial volume V and initial pressure P . Suppose the pressure is increased to $2P$, keeping the temperature and amount of gas molecules constant. What is the new volume?

- (a) $2V$ (b) $*V/2$ (c) $4V$ (d) $V/4$ (e) V

$$g = 9.81 \text{ m/s}^2 \quad G = 6.67 \times 10^{-11} \text{ N m}^2/\text{kg}^2$$

$$N_A = 6.022 \times 10^{23} \text{ things/mol}$$

$$k_B = 1.38065 \times 10^{-23} \text{ J} \cdot \text{K}^{-1}$$

$$R = 8.314 \text{ J/K-mol} = 8.314 \text{ L-kPa/K-mol}$$

$$\text{sphere } V = \frac{4}{3}\pi r^3 \quad A = 4\pi r^2$$

$$ax^2 + bx^2 + c = 0 \implies x = \frac{-b \pm \sqrt{b^2 - 4ac}}{2a}$$

$$\sin \alpha \pm \sin \beta = 2 \sin \frac{1}{2}(\alpha \pm \beta) \cos \frac{1}{2}(\alpha \mp \beta)$$

$$\cos \alpha \pm \cos \beta = 2 \cos \frac{1}{2}(\alpha + \beta) \cos \frac{1}{2}(\alpha - \beta)$$

$$c^2 = a^2 + b^2 - 2ab \cos \theta_{ab}$$

$$\frac{d}{dx} \sin ax = a \cos ax \quad \frac{d}{dx} \cos ax = -a \sin ax$$

$$\int \cos ax \, dx = \frac{1}{a} \sin ax \quad \int \sin ax \, dx = -\frac{1}{a} \cos ax$$

$$\sin \theta \approx \theta \quad \cos \theta \approx 1 - \frac{1}{2}\theta^2 \quad \text{small } \theta$$

$$\Delta \vec{r} = \vec{r}_f - \vec{r}_i$$

$$d \equiv |x_1 - x_2|$$

$$b \equiv |\vec{b}| = |b_x| \quad \text{one dimension}$$

$$\vec{r} = x \hat{i} \quad \text{one dimension}$$

$$\vec{b} = b_x \hat{i} \quad \text{one dimension}$$

$$\text{speed} = v = |\vec{v}|$$

$$\vec{v} = \lim_{\Delta t \rightarrow 0} \frac{\Delta \vec{r}}{\Delta t} \equiv \frac{d\vec{r}}{dt}$$

$$a_x = \lim_{\Delta t \rightarrow 0} \frac{\Delta v_x}{\Delta t} \equiv \frac{dv_x}{dt} = \frac{d}{dt} \left(\frac{dx}{dt} \right) = \frac{d^2 x}{dt^2}$$

$$\Delta v_x = \int_{t_i}^{t_f} a_x(t) \, dt \quad \Delta x = \int_{t_i}^{t_f} v_x(t) \, dt$$

$$x(t) = x_i + v_{x,i}t + \frac{1}{2}a_x t^2$$

$$v_x(t) = v_{x,i} + a_x t$$

$$v_{x,f}^2 = v_{x,i}^2 + 2a_x \Delta x$$

$$a_{x,\text{ramp}} = g \sin \theta$$

$$\Delta U^G = mg \Delta x$$

$$\frac{a_{1x}}{a_{2x}} = -\frac{m_2}{m_1}$$

$$E_{\text{mech}} = K + U \quad K = \frac{1}{2}mv^2$$

$$\Delta E = \Delta K + \Delta U = 0 \quad \text{non-dissipative, closed}$$

$$\Delta \vec{p} = \vec{0} \quad \text{isolated system}$$

$$\vec{p}_f = \vec{p}_i \quad \text{isolated system}$$

$$\vec{p} \equiv m\vec{v}$$

$$m_u = -\frac{\Delta v_{s,x}}{\Delta v_{u,x}} m_s$$

$$\vec{J} = \Delta \vec{p}$$

$$v_{1f} = \left(\frac{m_1 - m_2}{m_1 + m_2} \right) v_{i1} + \left(\frac{2m_2}{m_1 + m_2} \right) v_{2i} \quad \text{1D elastic}$$

$$v_{2f} = \left(\frac{2m_1}{m_1 + m_2} \right) v_{1i} + \left(\frac{m_2 - m_1}{m_1 + m_2} \right) v_{2i} \quad \text{1D elastic}$$

$$\Delta E = 0 \quad \text{isolated system}$$

$$K = \frac{1}{2}mv^2$$

$$\vec{v}_{12} = \vec{v}_2 - \vec{v}_1 \quad \text{relative velocity}$$

$$v_{12} = |\vec{v}_2 - \vec{v}_1| \quad \text{relative speed}$$

$$\vec{a} = \frac{\sum \vec{F}}{m} \quad \vec{a}_{\text{cm}} = \frac{\sum \vec{F}_{\text{ext}}}{m} \quad \sum \vec{F} \equiv \frac{d\vec{p}}{dt}$$

$$\vec{J} = \left(\sum \vec{F} \right) \Delta t = \Delta \vec{p} \quad \text{constant force}$$

$$\vec{J} = \int_{t_i}^{t_f} \sum \vec{F}(t) \, dt = \Delta \vec{p} \quad \text{time-varying force}$$

$$\vec{F}_{12} = -\vec{F}_{21} \quad F_{\text{grav}} = -mg \quad F_{\text{spring}} = -k\Delta x$$

$$\Delta E = W$$

$$\Delta U_{\text{spring}} = \frac{1}{2}k(x - x_o)^2$$

$$P = \frac{dE}{dt}$$

$$P = F_{\text{ext},x} v_x \quad \text{one dimension}$$

Rotation: we use radians

$$s = \theta r \quad \leftarrow \text{arclength}$$

$$\omega = \frac{d\theta}{dt} = \frac{v_t}{r} \quad \alpha = \frac{d\omega}{dt}$$

$$a_t = \alpha r \quad \text{tangential} \quad a_r = -\frac{v^2}{r} = -\omega^2 r \quad \text{radial}$$

$$v_t = r\omega \quad v_r = 0$$

$$\begin{aligned}
(F_{12}^s)_{\max} &= \mu_s F_{12}^n \\
F_{12}^k &= \mu_k F_{12}^n \\
\vec{A} &= \vec{A}_x + \vec{A}_y = A_x \hat{i} + A_y \hat{j} \\
\vec{A} \cdot \vec{B} &= AB \cos \phi = A_x B_x + A_y B_y \\
W &= \vec{F} \cdot \Delta \vec{r}_F \quad \text{const non-diss force} \\
W &= \int_{\vec{r}_i}^{\vec{r}_f} \vec{F}(\vec{r}) \cdot d\vec{r} \quad \text{variable nondiss force} \\
&\downarrow \text{launched from origin, level ground} \\
y(x) &= (\tan \theta_o) x - \frac{gx^2}{2v_o^2 \cos^2 \theta_o} \\
\text{max height} = H &= \frac{v_i^2 \sin^2 \theta_i}{2g} \\
\text{Range} = R &= \frac{v_i^2 \sin 2\theta_i}{g}
\end{aligned}$$

fluids:

$$\begin{aligned}
P &= F/A \\
P(d) &= P_{\text{surface}} + \rho g d \\
\rho &= M/V \\
\frac{F_1}{A_1} &= \frac{F_2}{A_2} \quad F_1 x_1 = F_2 x_2 \quad \text{hydraulics} \\
B &= \text{buoyant force} = \text{weight of water displaced} = \rho_f V_{\text{displ}} g \\
P &= P_{\text{gauge}} + P_{\text{atm}}
\end{aligned}$$

thermal stuff:

$$\begin{aligned}
PV &= Nk_B T = nRT \\
T(K) &= T(^{\circ}C) + 273.15^{\circ} \\
Q &= mc\Delta T \quad c = \text{specific heat} \quad \text{no phase chg} \\
Q &= \pm mL \quad \text{phase chg}
\end{aligned}$$

$$I = \sum_i m_i r_i^2 \Rightarrow \int r^2 dm = kmr^2 \quad I = mr^2 \quad \text{point particle}$$

$$I_z = I_{\text{com}} + md^2 \quad \text{axis } z \text{ parallel, dist } d$$

$$\vec{L} = \vec{r} \times \vec{p} = I\vec{\omega}$$

$$K = \frac{1}{2} I \omega^2 = L^2 / 2I$$

$$\Delta K = \frac{1}{2} I \omega_f^2 - \frac{1}{2} I \omega_i^2 = W = \int \tau d\theta$$

$$P = \frac{dW}{dt} = \tau \omega$$

$$\tau = rF \sin \theta_r = r_{\perp} F = r F_{\perp}$$

$$\tau_{\text{net}} = \sum \vec{\tau} = I \vec{\alpha} = \frac{d\vec{L}}{dt}$$

$$K_{\text{tot}} = K_{\text{cm}} + K_{\text{rot}} = \frac{1}{2} m v_{\text{cm}}^2 + \frac{1}{2} I \omega^2$$

Oscillations:

$$T = \frac{1}{f} = \frac{2\pi}{\omega} \quad \omega = \frac{2\pi}{T} = 2\pi f$$

$$x(t) = A \sin(\omega t + \varphi_i)$$

$$v(t) = \frac{dx}{dt} = \omega A \cos(\omega t + \varphi_i)$$

$$a(t) = \frac{d^2x}{dt^2} = -\omega^2 A \sin(\omega t + \varphi_i)$$

$$\varphi(t) = \omega t + \varphi_i$$

$$a = -\omega^2 x \quad \frac{d^2x}{dt^2} = -\omega^2 x \quad \frac{d^2\theta}{dt^2} = -\omega^2 \theta$$

$$E = \frac{1}{2} m \omega^2 A^2$$

$$\omega = \sqrt{k/m} \quad \text{spring.}$$

$$T = \begin{cases} 2\pi\sqrt{L/g} & \text{simple pendulum} \\ 2\pi\sqrt{I/mgl_{\text{cm}}} & \text{physical pendulum} \end{cases}$$

Waves:

$$y = f(x - ct) \quad \text{along } +x \quad y = f(x + ct) \quad \text{along } -x$$

$$k = \frac{2\pi}{\lambda} \quad \lambda = cT \quad \omega = \frac{2\pi}{T} \quad c = \lambda f$$

$$y(x, t) = f(x, t) = A \sin(kx - \omega t + \varphi_i)$$

$$y(x, t) = 2A \sin kx \cos \omega t \quad \text{standing wave}$$

$$\text{nodes at } x = 0, \pm \frac{\lambda}{2}, \pm \lambda, \pm \frac{3\lambda}{2}$$

$$v = \sqrt{T/\mu} \quad \mu = M_{\text{string}}/L_{\text{string}} \quad T = \text{tension} \quad \text{strings}$$

$$P_{\text{av}} = \frac{1}{2} \mu \lambda A^2 \omega^2 / T = \frac{1}{2} \mu A^2 \omega^2 c$$

$$\frac{\partial^2 f}{\partial x^2} = \frac{1}{c^2} \frac{\partial^2 f}{\partial t^2}$$

$$f_n = \frac{nv}{\lambda} = \frac{nv}{2L} \quad \lambda_n = \frac{2L}{n} \quad n = 1, 2, 3, \dots \quad \text{strings \& open-open pipe}$$

$$f_n = \frac{nv}{\lambda} = \frac{nv}{4L} \quad \lambda_n = \frac{4L}{n} \quad n = 1, 3, 5, \dots \quad \text{closed-open pipe}$$

Isolated systems: \vec{p} , $E = K + PE$, L are all conserved.

Static equilibrium: $\sum F = 0$ and $\sum \tau = 0$ about any axis.

Elastic collision: KE and p are both conserved.

Inelastic collision: only p is conserved, not KE.

Derived unit	Symbol	equivalent to
newton	N	kg·m/s ²
joule	J	kg·m ² /s ² = N·m
watt	W	J/s = m ² ·kg/s ³

Power Prefix Abbreviation

10 ⁻¹²	pico	p
10 ⁻⁹	nano	n
10 ⁻⁶	micro	μ
10 ⁻³	milli	m
10 ⁻²	centi	c
10 ³	kilo	k
10 ⁶	mega	M
10 ⁹	giga	G
10 ¹²	tera	T